

Surname, First name

1	1	1	1	1	1	1
2	2	2	2	2	2	2
3	3	3	3	3	3	3
4	4	4	4	4	4	4
5	5	5	5	5	5	5
6	6	6	6	6	6	6
7	7	7	7	7	7	7
8	8	8	8	8	8	8
9	9	9	9	9	9	9
0	0	0	0	0	0	0

### Modelling, Uncertainty and Data for Engineers EXAM (CEGM1000)

Exam Q1

4 Nov, 2024, 13:30-16:30

a  b  c  d  e  f → b

a  b  c  d  e  f → c

a  b  c  d  e  f → a

a  b  c  d  e  f → b, d

a  b  c  d  e  f → c

a  b  c  d  e  f → a, d

Answer multiple-choice questions as shown in the example. Circular checkboxes have only one correct answer. Square checkboxes may have multiple correct answers.

Dear student,

Before you start the exam, a few remarks:

- Write down your first and last name in the field on the top left corner of this page
- Fill in your student number on the top right corner of this pages. Fill in the number in the boxes on top, and mark the corresponding number. Fill the corresponding circle with the number completely.
- The duration of the exam is 3 hours. If you're entitled to time extension, you have 3,5 hours.
- It is not allowed to release the staple.
- (Graphical) calculators are allowed, as long as they do not include document viewing or network connection capabilities.
- Any other tools and sources of information are not allowed.
- This answer sheet contains both the questions as an answer field. It is unique per student, as a result of which you are not able to obtain a new answer sheet. In case you want to erase and rewrite your answer, ask an invigilator for a white sticker to cover your incorrect answer. Furthermore, this answer sheet contains some additional space for your answers. You can use this if you need run out of space at the original answer field. If you use this additional space, please indicate so at the original answer field.
- For your convenience, a separate formula sheet is provided. These appendices will not be graded.
- Scrap paper is not graded.

Good luck!

Kind regards, the MUDE team

## Exercise 1: Programming

### Programming part I: Object-oriented programming

Consider the following piece of code and output, and reflect on the object oriented programming (OOP) that is used:

```
[ ]: import numpy as np
      data = np.genfromtxt(...)
      print(data.shape)
      print(data.mean())
```

Output:

```
(2734, )
```

```
65.4
```

2p **1a** Which of the following are OOP **attributes**? (You can select more than 1)

- data
- np
- numpy
- genfromtext
- print
- shape
- mean
- none of the above



2p **1b** which of the following are OOP **methods**? (You can select more than 1)

- data
- np
- numpy
- genfromtext
- print
- shape
- mean
- none of the above

## Programming part II: Errors

A friend has sent you a piece of code (not provided) that is supposed to compute the numerical solution to an ordinary differential equation using Taylor series, an iteration scheme and a numpy array. However, instead of getting the expected answer of 5, the code returns 9.

3p **1c** What type of error is this? Add an explanation for your reasoning.


3p **1d** What would be a useful approach to help figure out and solve the problem? Consider each of the following and select **one** that you would find useful. Add an explanation for your selection.

- Read the traceback
- Use list comprehension
- Try pandas instead of numpy
- Use assert statements

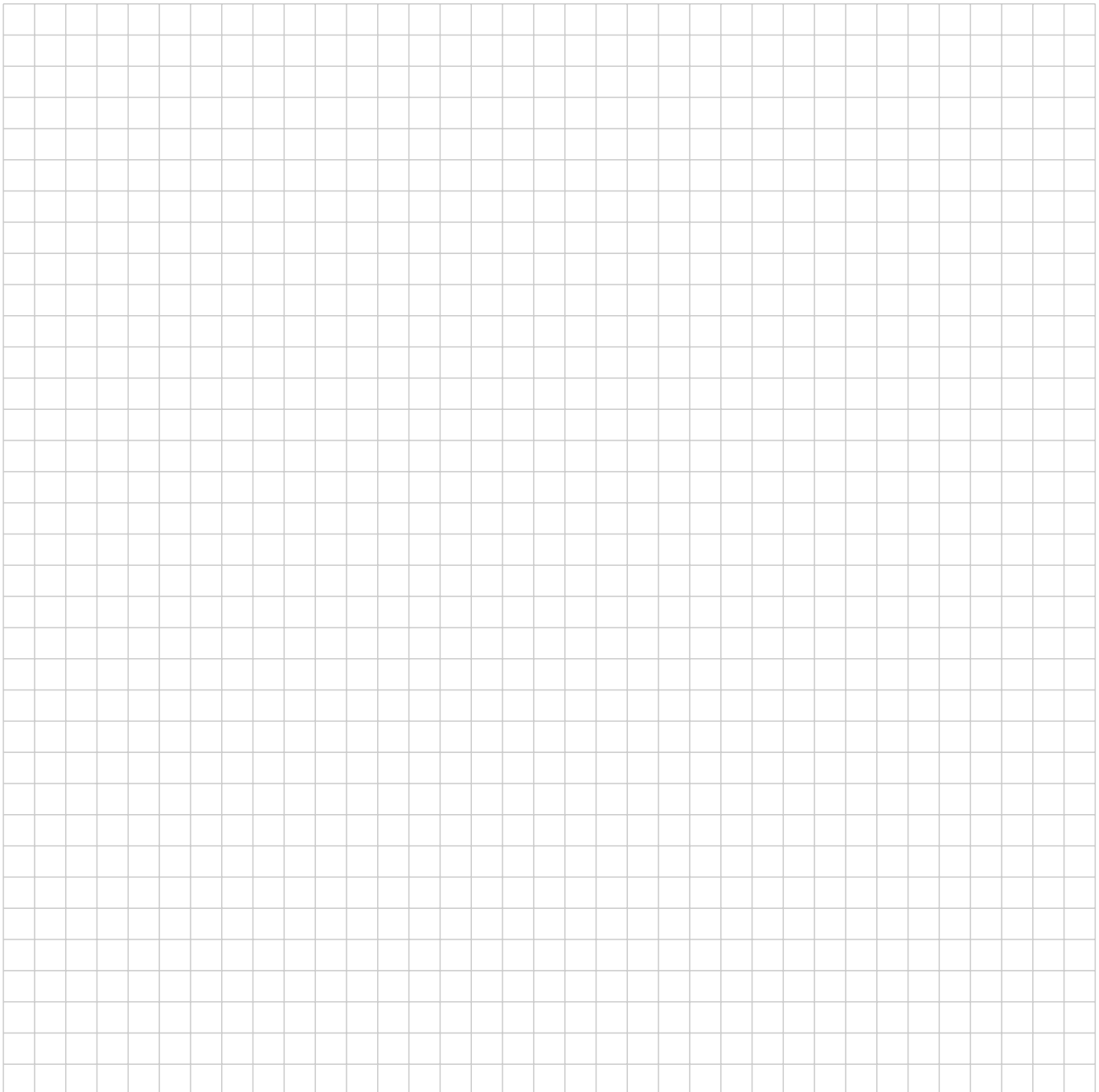



**Exercise 2: Uncertainty Propagation**

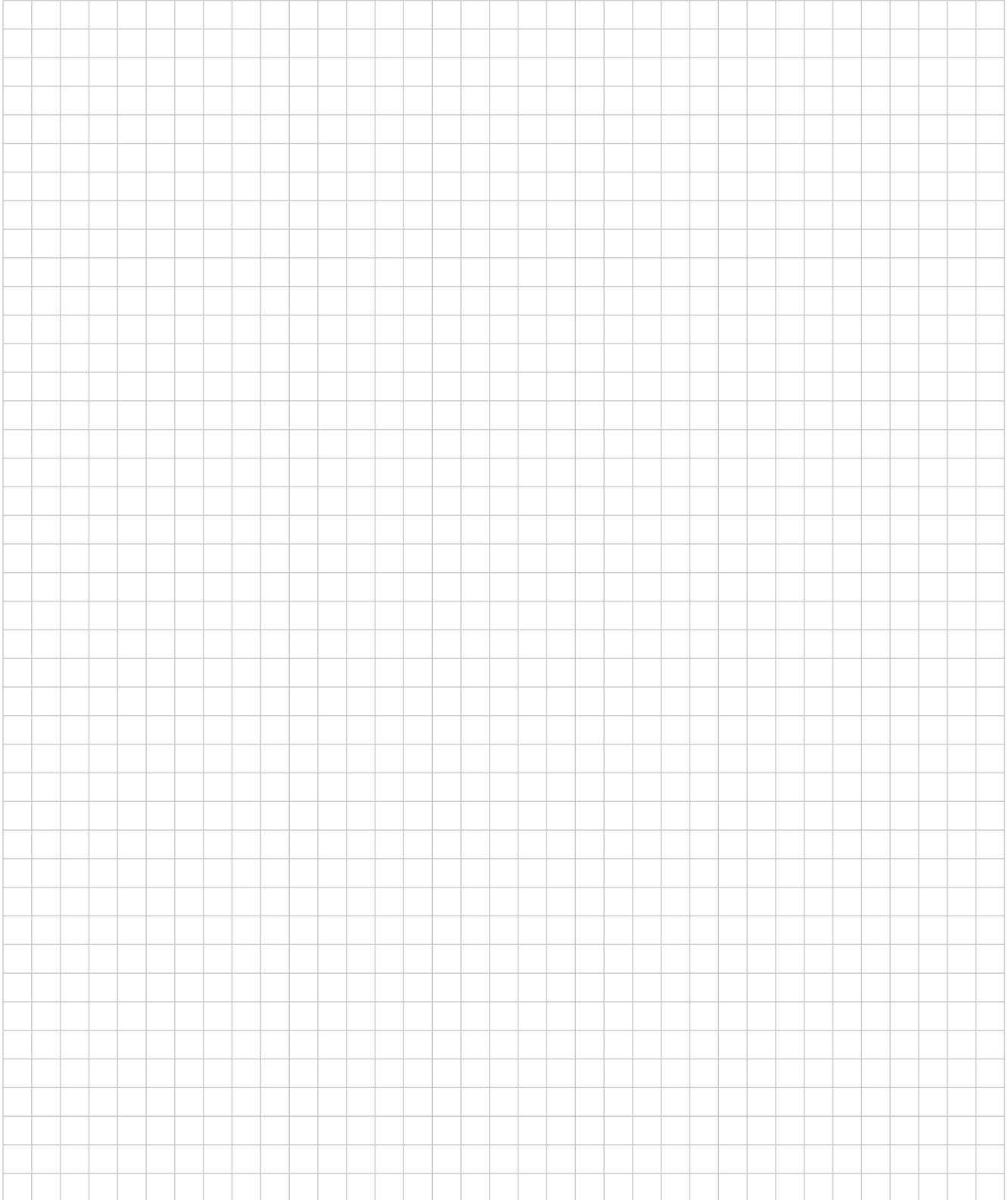
Let  $X_1, X_2, X_3$ , be independent random variables, each following a standard normal distribution. These random variables are combined into a 3-dimensional random vector  $Y = [Y_1, Y_2, Y_3]^T$ , defined as:

$$Y = \begin{bmatrix} X_1 \\ X_2 + X_3 \\ X_1 + X_2 + X_3 \end{bmatrix}$$

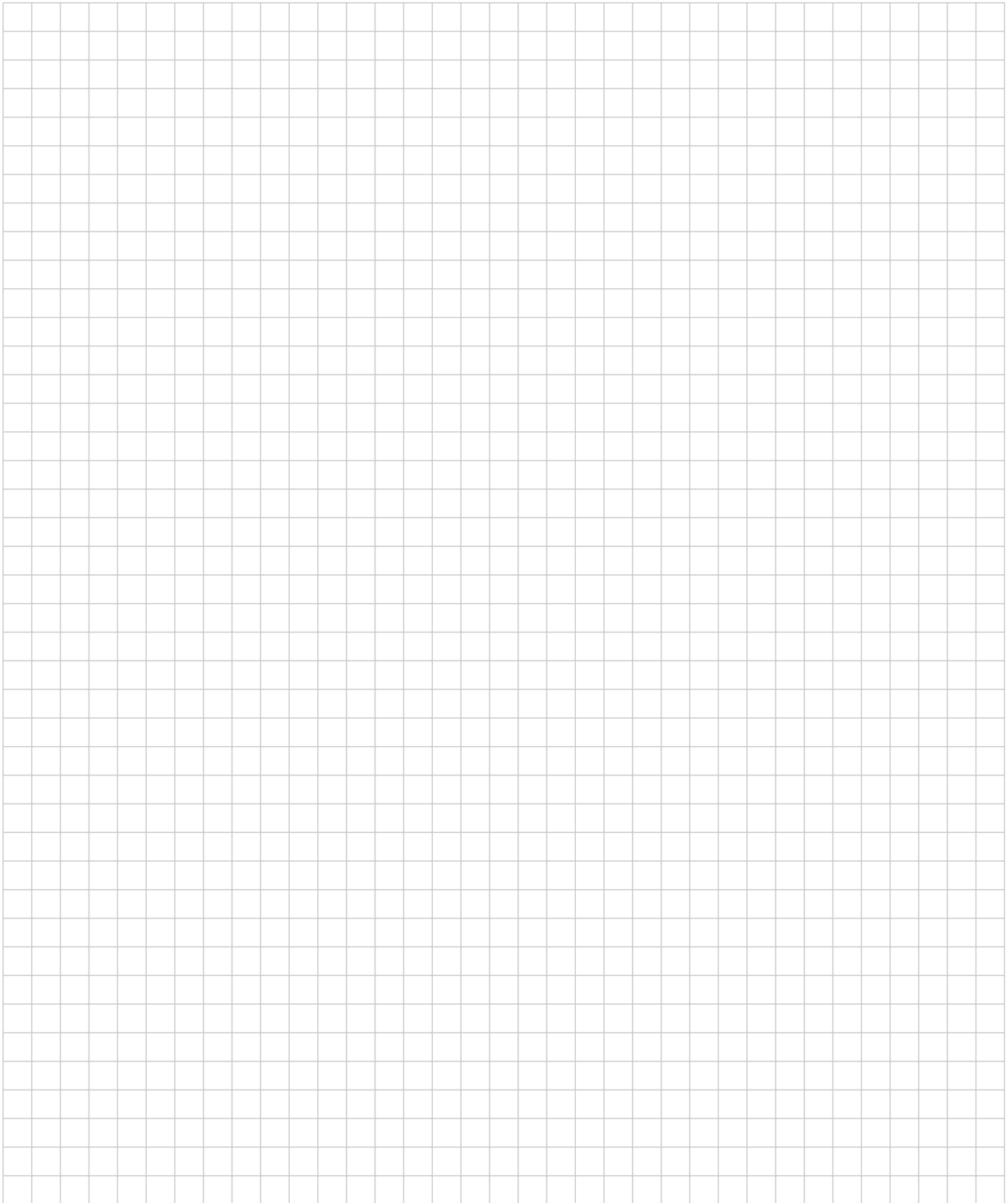
4p **2a** What is the expectation of  $Y$ ?



8p **2b** Apply the propagation law to show that  $\text{cov}(Y_1, Y_2) = 0$  and **explain** why this is the case?



- 6p **2c** If the second element of  $Y$  is changed to  $X_2 - X_3$ , which elements in covariance matrix of the changed vector  $Y$ ,  $\Sigma_Y$ , will be changed? Write out the new  $\Sigma_Y$ .



**Exercise 3: Observation theory**

An object is moving along a straight line with an unknown speed  $v$ . It starts at  $t_0 = 0 [s]$  with the known location  $x_0 = 0 [m]$ . We measured its location every  $\Delta t$  seconds and obtained  $m$  measurements  $y_i$ , where  $i = [1, \dots, m]$ , measured at  $t_i = i \cdot \Delta t$ .

**Model 1:**  $y_i = x_0 + vt_i$

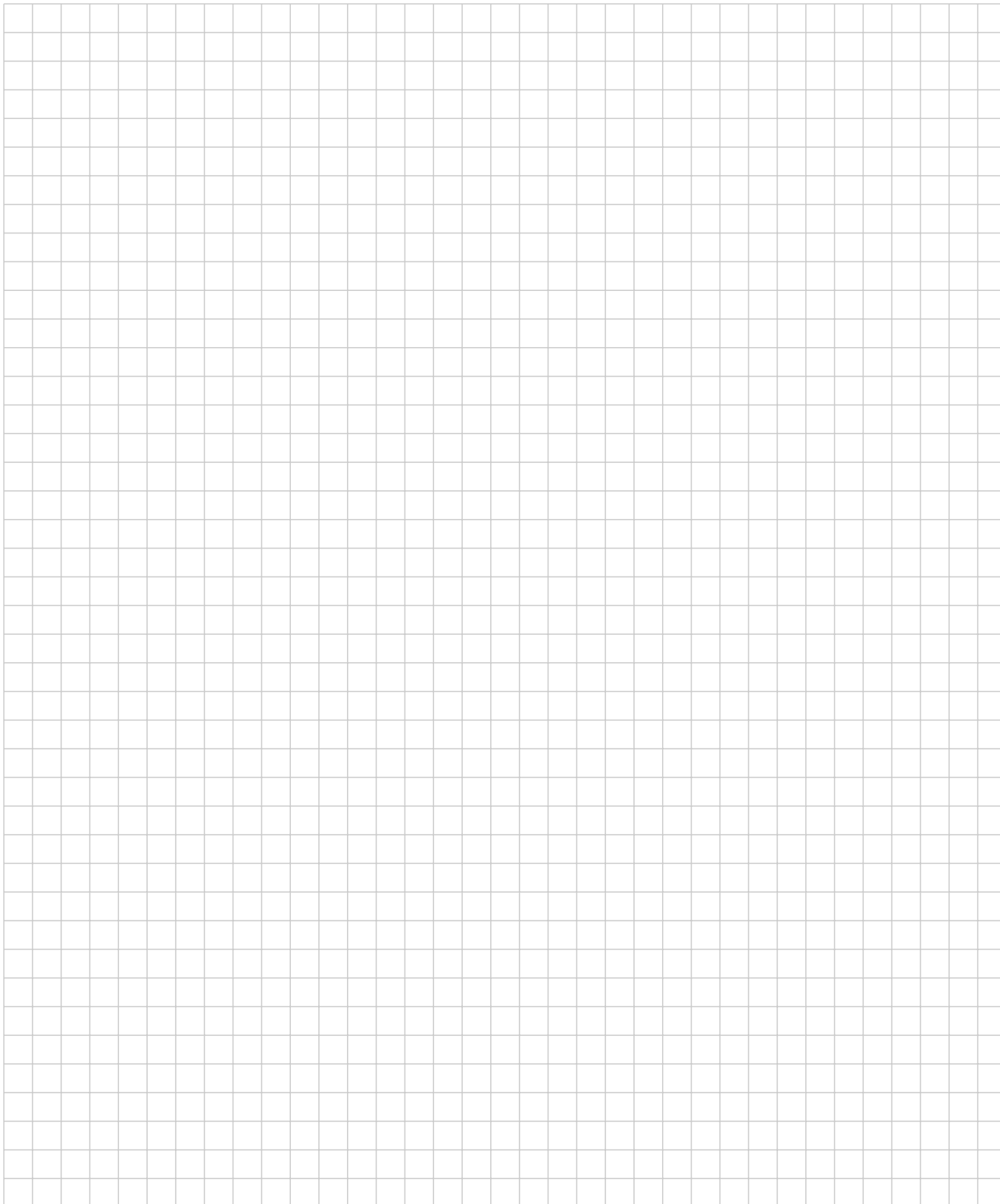
We assume the measurements  $y_i$  are independent and follow a normal distribution with standard deviation  $\sigma_i = i \cdot \sigma$

6p **3a** Specify the functional model and the covariance matrix of the observable,  $\Sigma_Y$ , according to Model 1.





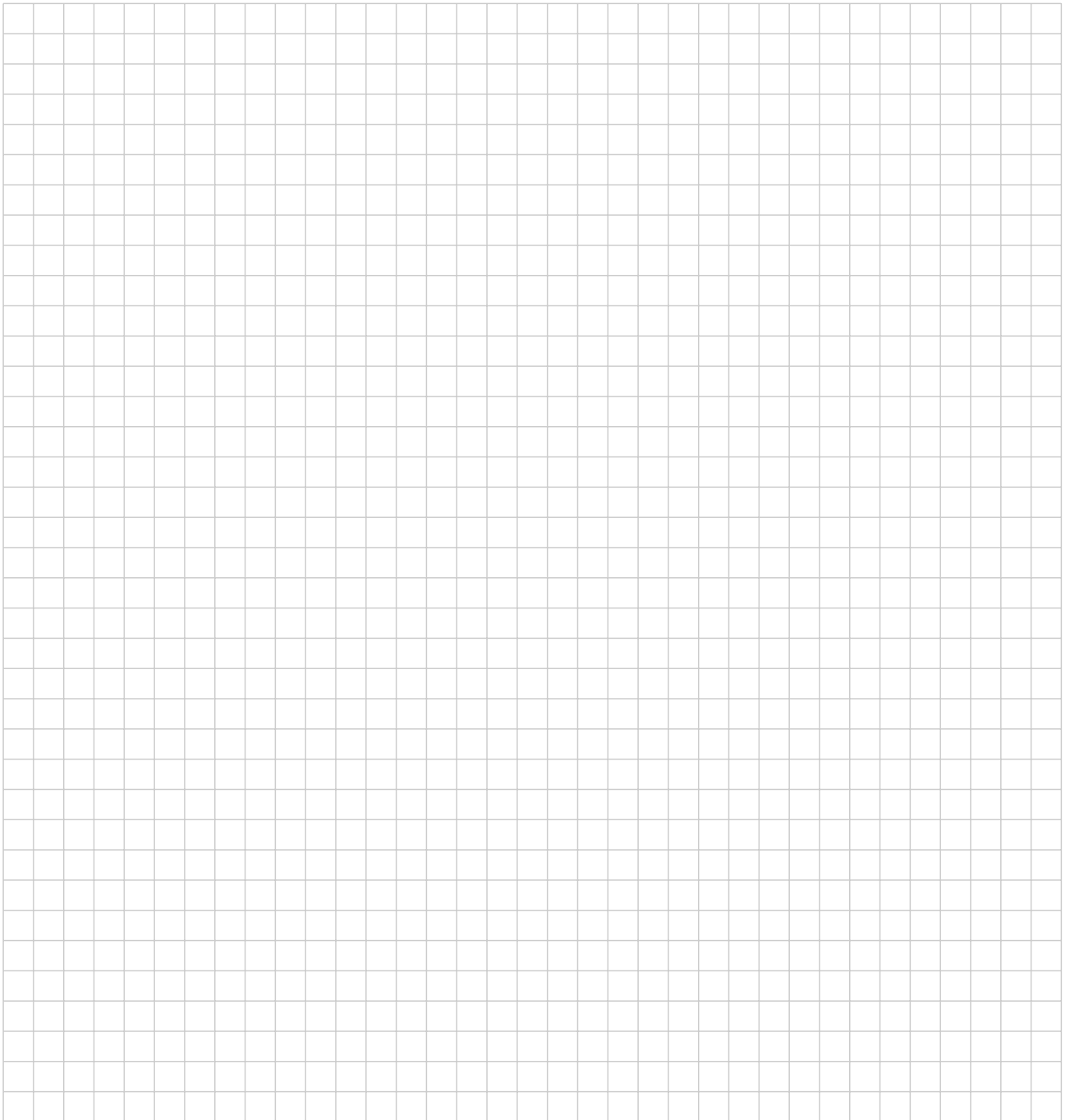
- 6p **3b** How many measurements  $m$  are required if we want the 99% confidence interval to be no larger than  $\hat{v} \pm 0.2[m/s]$ ? Assume  $\sigma = 0.4[m]$  and  $\Delta t = 2[s]$



Another engineer assumes the initial position  $x_0$  to be unknown, and that the movement may have an unknown acceleration  $a$ :

**Model 2:**  $y_i = x_0 + vt_i + \frac{1}{2}at_i^2$

- 6p **3c** Which test should the engineer apply **and** what is the corresponding critical value used for significance level  $\alpha = 0.05$ ? Answer the questions **without** specifying the functional model of Model 2.



**Exercise 4: Numerical Modeling**

8p **4a** Use the Newton-Raphson method to solve for  $x$  in the following equation:

$$x^5 + 3x = 100$$

Recall that:

$$x_{j+1} = x_j - \frac{g(x_j)}{g'(x_j)}$$

Where  $g(x) = 0$  and  $j$  is the iteration number.

Write down the equation to be iterated in the Newton-Raphson method.

Assume a first guess of  $x = 2$ , then compute the second guess (i.e., one iteration).



2p **4b** What is the error order of the Taylor Series Expansion (TSE) of:  $x^2 - a$  using the first 3 terms  $\left[ f(x_i) + \Delta x f'(x_i) + \frac{(\Delta x)^2}{2!} f''(x_i) \right]$ , where  $a$  is a constant.

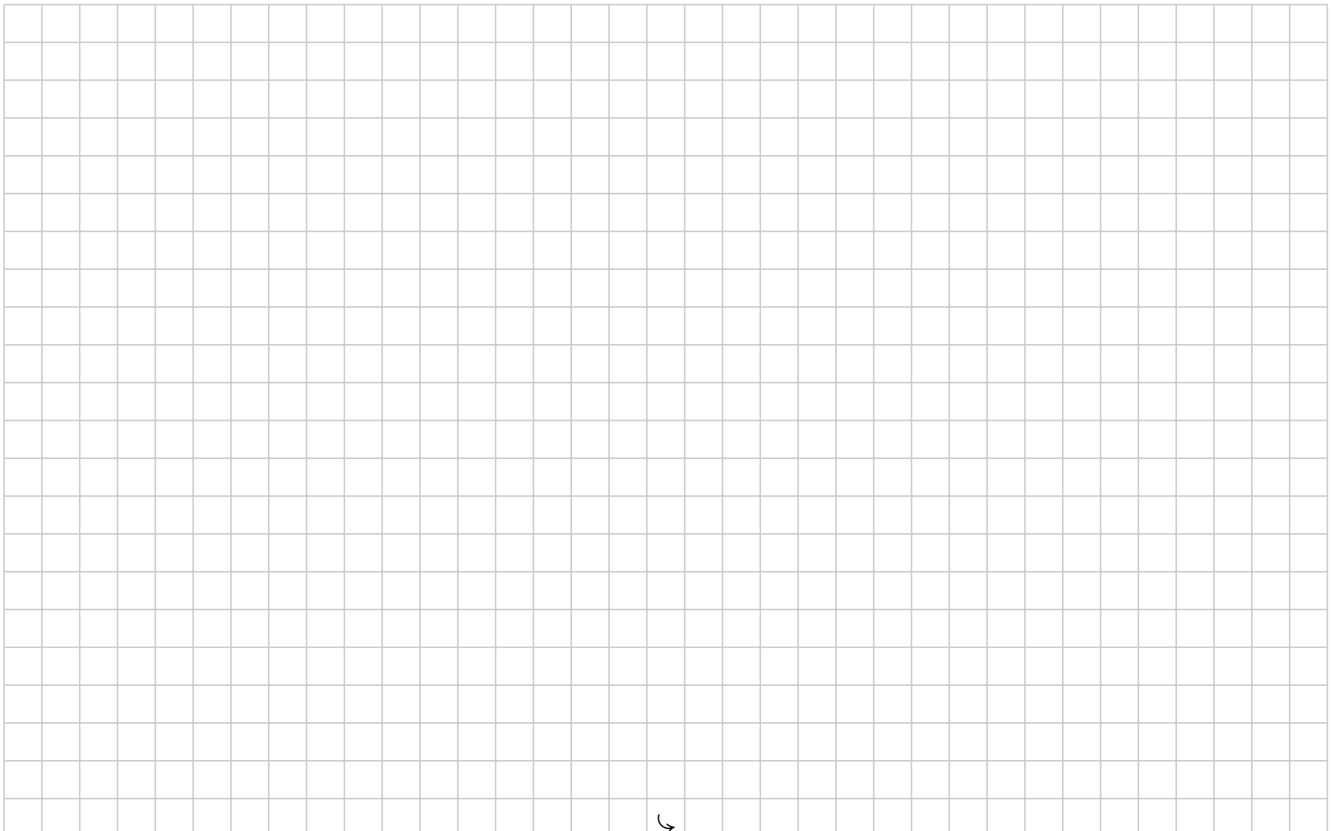
- (a) There is no error
- (b)  $\mathcal{O}(\Delta x)$ .
- (c)  $\mathcal{O}(\Delta x^2)$ .
- (d)  $\mathcal{O}(\Delta x^3)$ .
- (e)  $\mathcal{O}(\Delta x^4)$ .

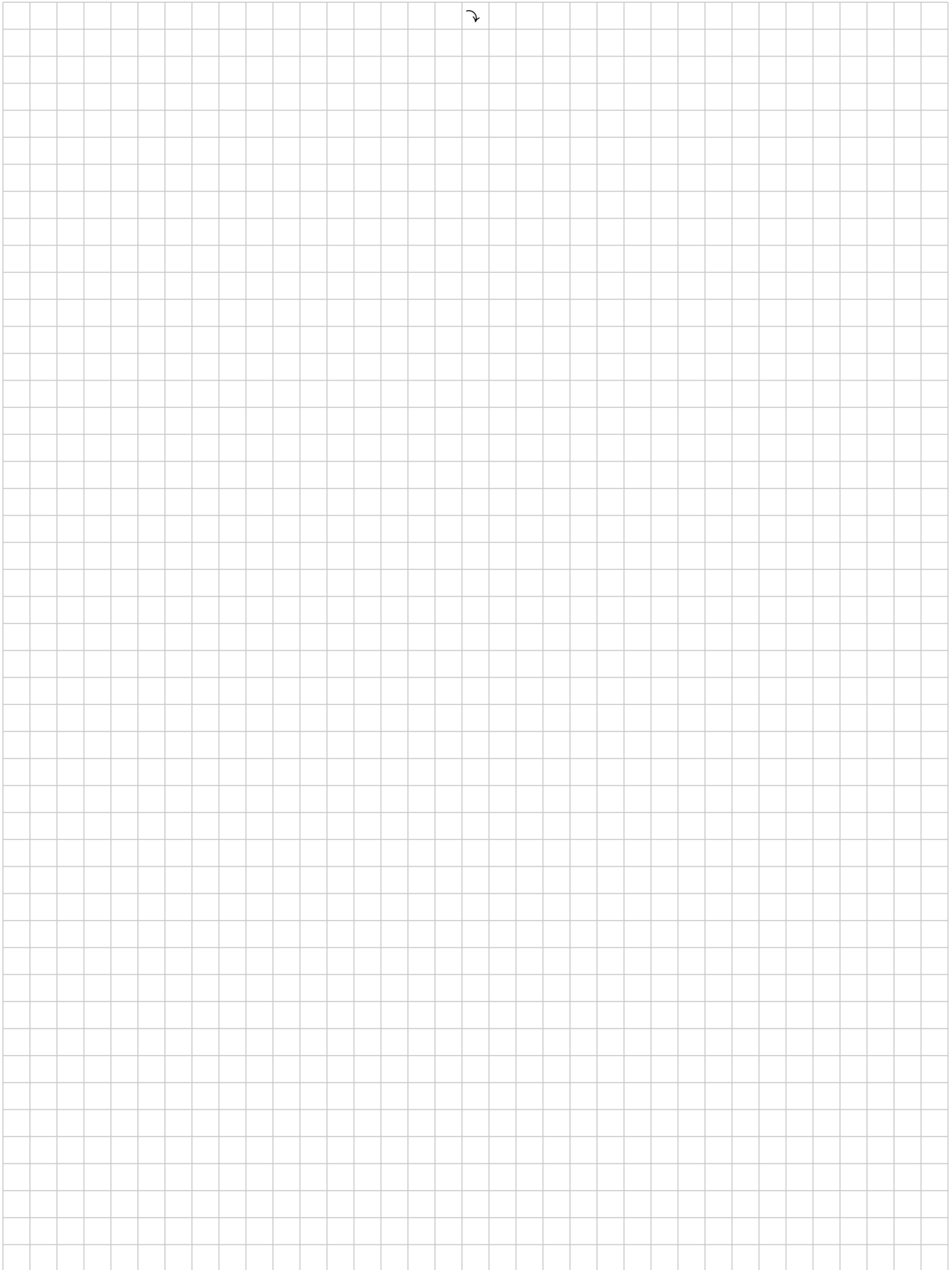
6p **4c** Use Forward Euler to approximate the solution of the following Initial Value Problem from  $t = 0$  until  $t = 0.2$ :

$$\frac{dy}{dt} = y + \sin(t)$$

$$y(t_0 = 0) = 1$$

$$\Delta t = 0.1$$





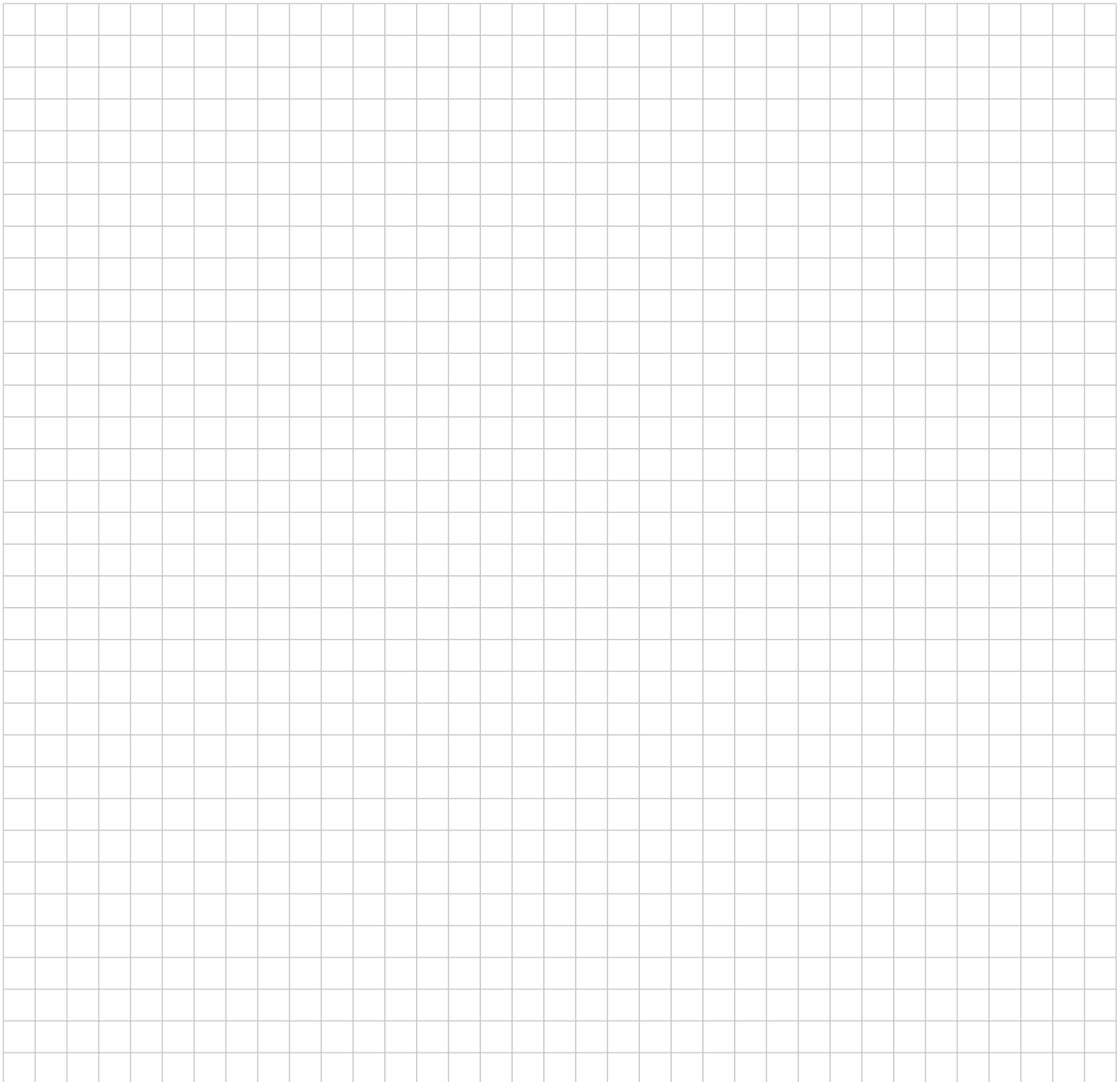
2p **4d** Is Backward Euler more accurate than Forward Euler?

- a Yes     b No

5p **4e** Consider the following convection equation:

$$\frac{dc}{dt} + v \frac{dc}{dx}$$

Specify how many initial conditions and boundary conditions are required to solve the convection equation. **Then**, write the algebraic expression to approximate the first derivative of this PDE using: Central difference in space **and** central difference in time



- 6p **4f** Consider a grid with 5 nodes:  $x_0, x_1, x_2, x_3, x_4$ . The temperature profile on this grid is described by the discretized ODE:

$$\frac{1}{\Delta x^2}(T_{i-1} - 2T_i + T_{i+1}) - \alpha(T_i - T_0) = 0$$

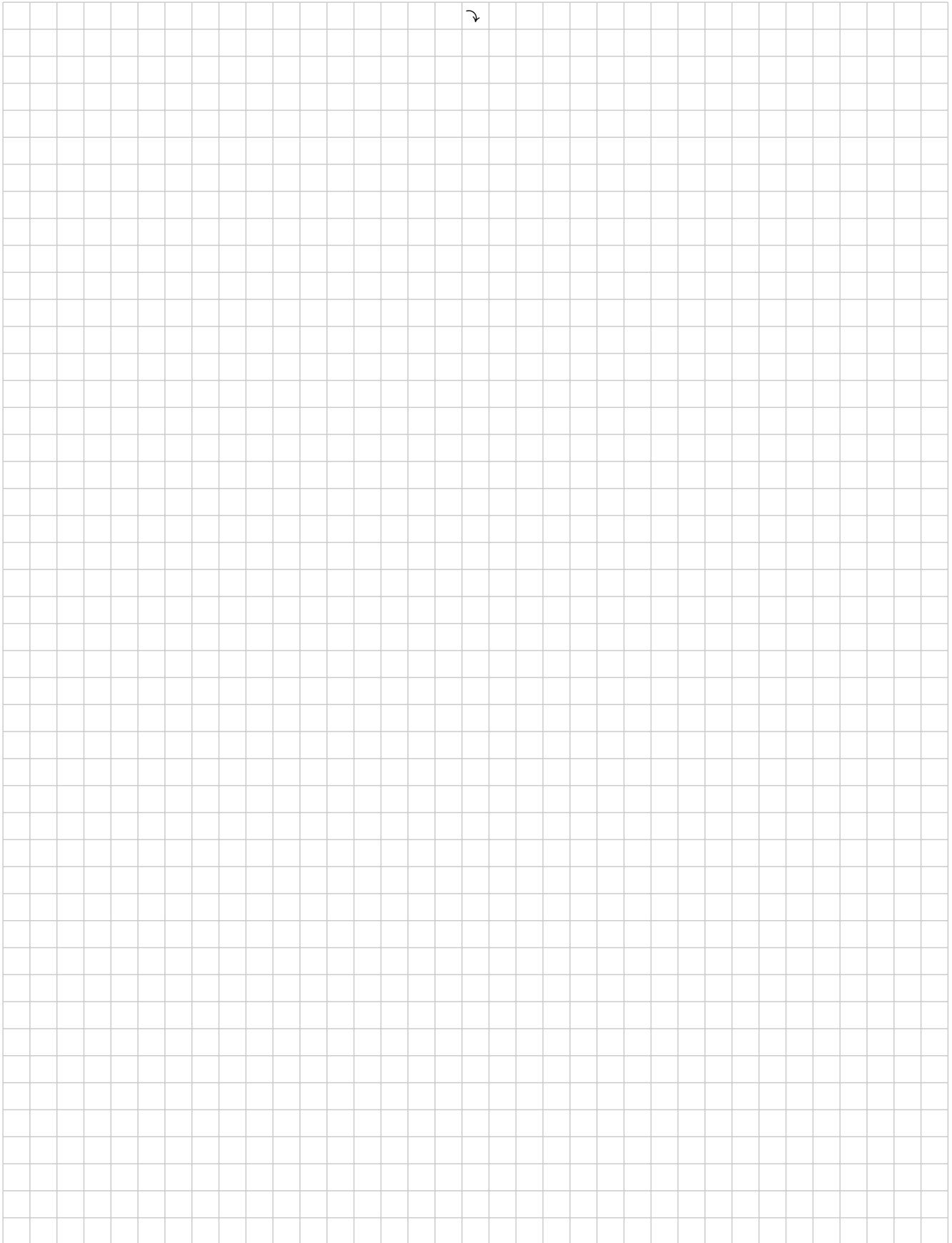
where  $\alpha$ ,  $\Delta x$  and  $T_s$  are known constants. The boundary conditions are Dirichlet:

$$T(x_0) = T_0 \text{ and } T(x_4) = T_4$$

A fellow student proposes the following system to solve the problem:

$$\begin{bmatrix} -(2 + \alpha\Delta x^2) & 1 & 0 \\ 1 & -(2 + \alpha\Delta x^2) & 1 \\ 0 & 1 & -(2 + \alpha\Delta x^2) \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = \begin{bmatrix} \alpha T_s \Delta x^2 \\ \alpha T_s \Delta x^2 \\ \alpha T_s \Delta x^2 \end{bmatrix}$$

Explain what is wrong with this proposed system. How would you correct it?





### Exercise 5: Probability and Reliability

The empirical or sample mean based on  $m$  outcomes (or: realizations)  $x_i$  can be computed as:

$$\hat{\mu}_X = \frac{1}{m} \sum_{i=1}^m x_i$$

The sample variance can be computed as:

$$\hat{\sigma}_X^2 = \frac{1}{m-1} \sum_{i=1}^m (x_i - \hat{\mu}_X)^2$$

Finally, the covariance is given by:

$$Cov(X_1, X_2) = \mathbb{E}([X_1 - \mathbb{E}(X_1)][X_2 - \mathbb{E}(X_2)])$$

A group of scientists are analyzing the influence of ice water content in the clouds  $[IC, kg/m^2]$  on rainfall  $[RF, mm]$  as their theory is that it will improve the development of weather and climate models. Here you have a brief definition of the variables:

- Ice water content in the clouds  $[IC, kg/m^2]$ . It is the amount of ice that you have in the clouds on the column of air above a given area. Thus, only positive values have a physical meaning.
- Rainfall  $[RF, mm]$ . Here, it is defined as the amount of rain that was accumulated during the hour when the measurement was conducted in the area used to compute  $IC$ . Again, only positive values have a physical meaning.

They have been able to conduct 10 field measurements that are shown in the table below:

$IC [kg/m^2]$	$RF [mm]$
999	10
242	8
76	7
666	4
1292	12
927	9
405	9.5
126	7
867	6
491	10

Table 1: Pair observations of ice water content and rainfall.

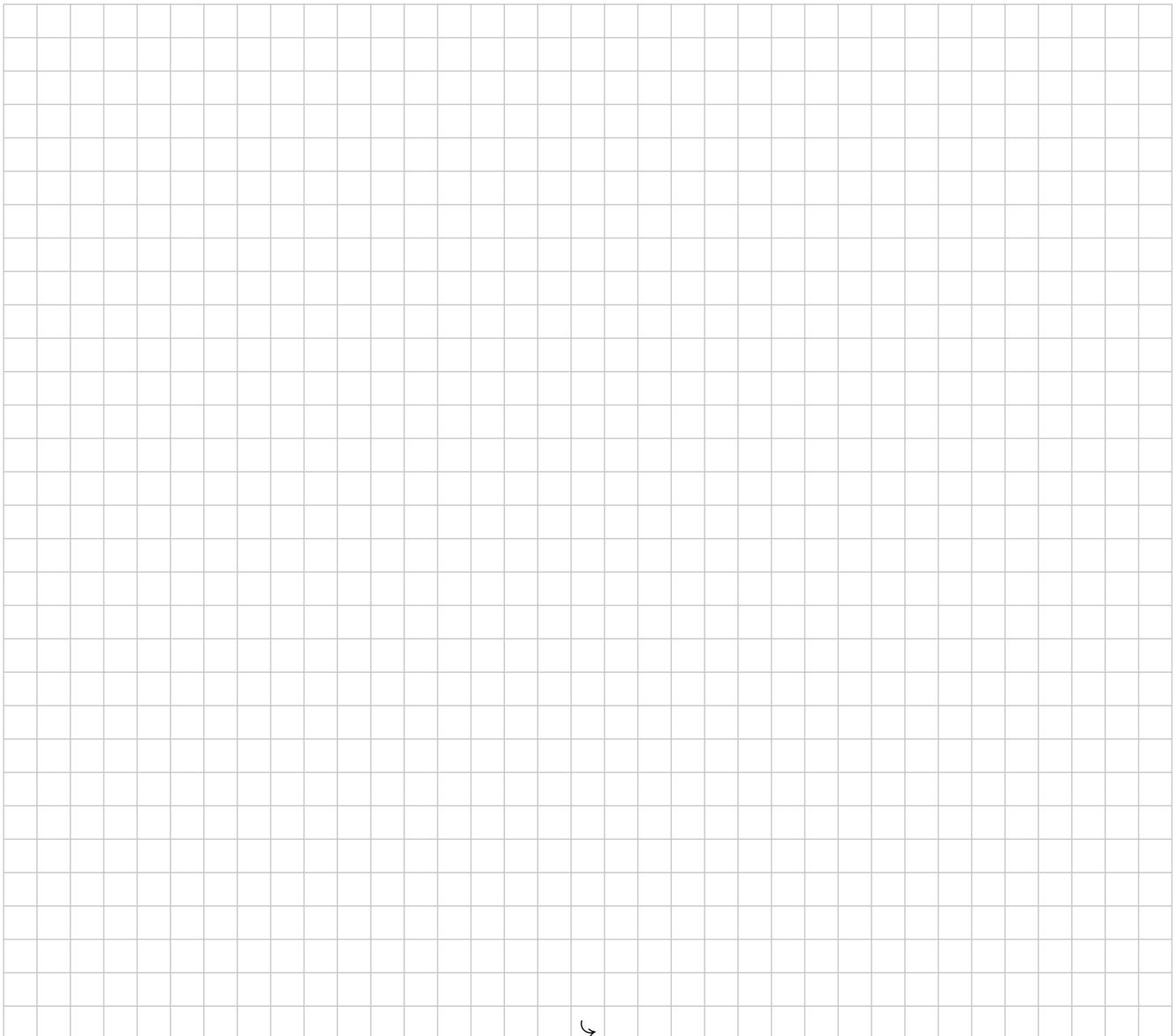
*Disclaimer: this example and data are generated for academic purposes.*

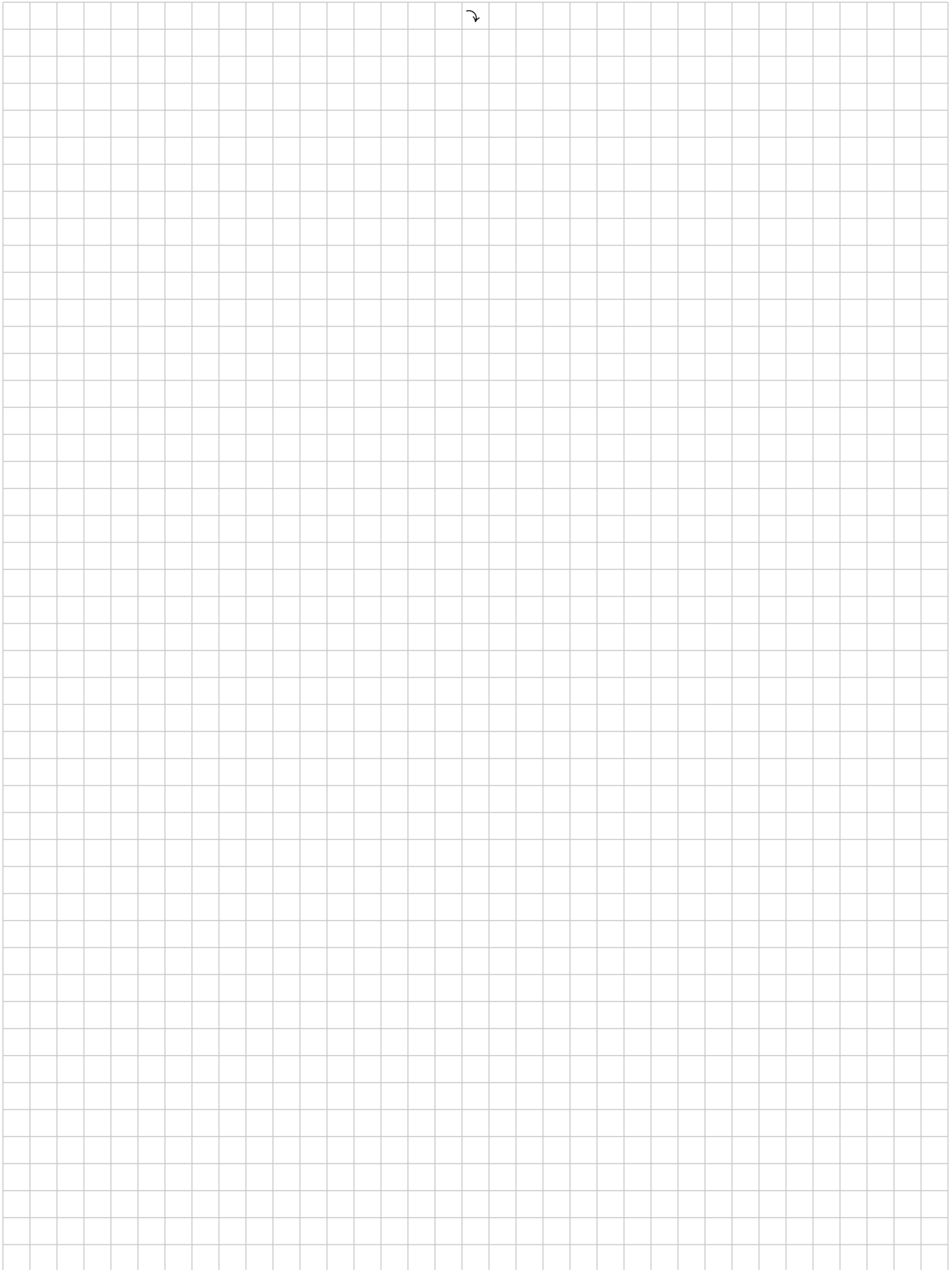
2p **5a** What do PDF and CDF stand for? Choose the right combination of words.

- a P-value Distribution Function, and Cumulative Distribution Function
- b Probability Density Function, and Cumulative Distribution Function
- c Probability Distribution Function, and Cumulative Density Function
- d Probability Density Function, and Cumulative Density Function

6p **5b** Compute and draw the empirical CDF of the variable  $IC$ .

Remember to label the axis and indicate their values. You may want to arrange your calculations in table format.

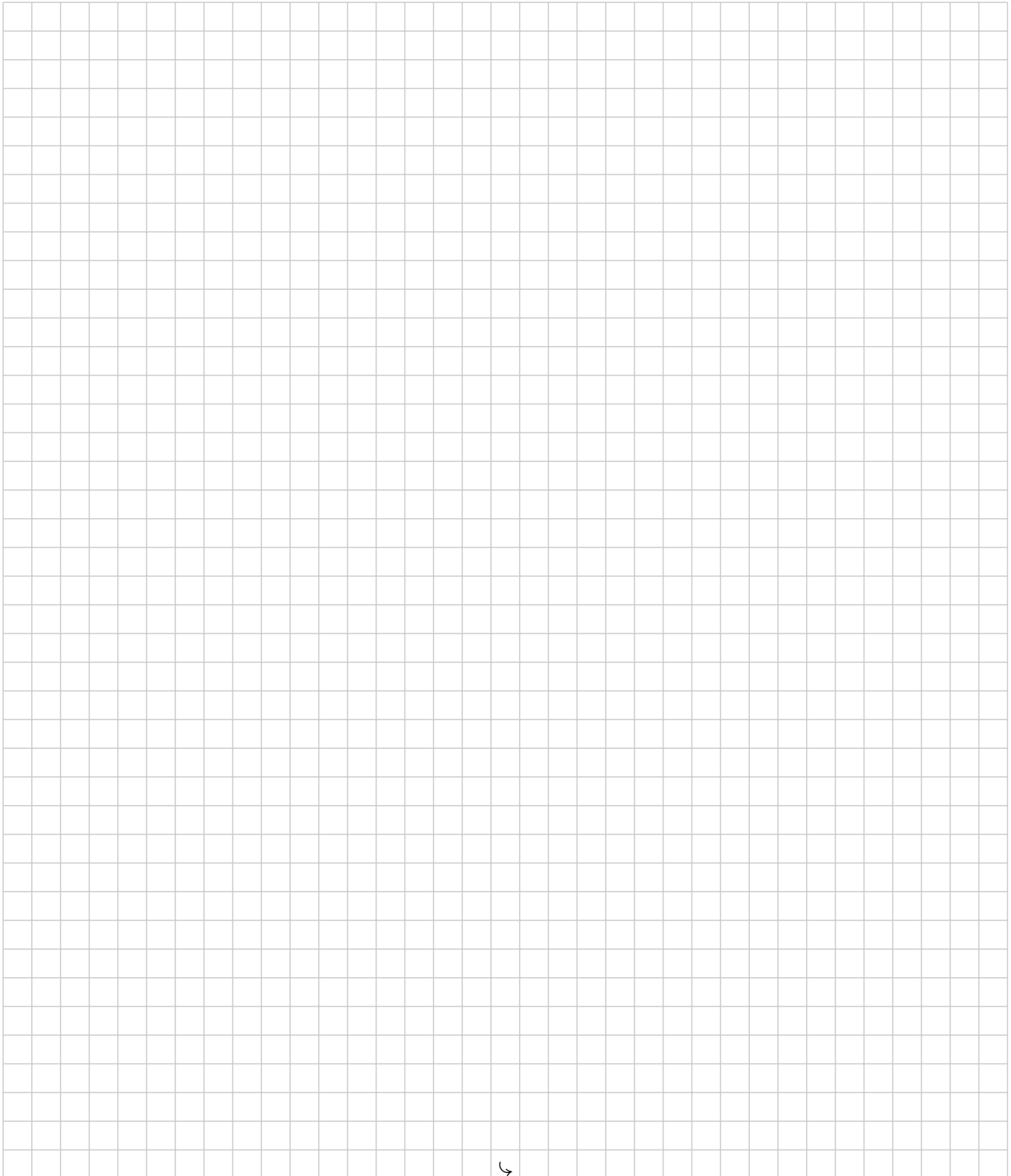






- 8p **5e** Assuming that the scientists want to quantify the joint distribution function of  $IC$  and  $RF$  using a multivariate Gaussian distribution.

Compute the covariance matrix of  $IC$  and  $RF$ . Do not use more than two decimal figures. You may want to make use of a table format to arrange your calculations.



A large grid of graph paper for calculations, consisting of 20 columns and 30 rows of small squares. A small arrow cursor is visible near the bottom center of the grid.

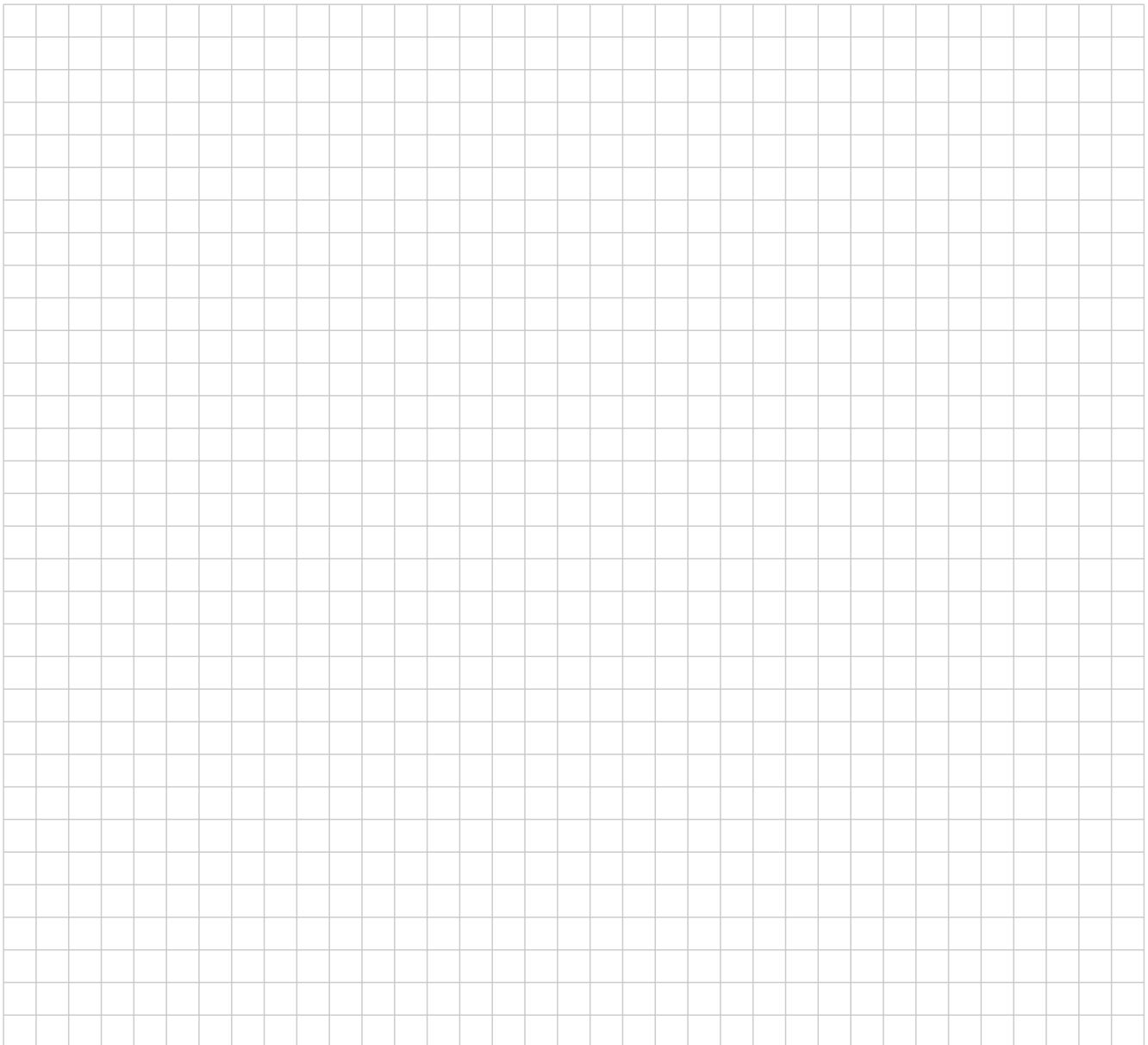




4p **5f** Assume that finally the scientists have changed their mind and do NOT want to quantify the joint distribution function of  $IC$  and  $RF$  using a multivariate Gaussian distribution. They have derived marginal distributions for  $IC$ ,  $RF$  and the joint distribution of  $IC$  and  $RF$  as follows:

- The marginal distribution of  $IC$  is given by the PDF  $f_{IC}(ic)$  and the CDF  $F_{IC}(ic)$ .
- The marginal distribution of  $RF$  is given by the PDF  $f_{RF}(rf)$  and the CDF  $F_{RF}(rf)$ .
- The joint probability distribution of  $IC$  and  $RF$  is given by the PDF  $f_{IC,RF}(ic,rf)$  and the CDF  $F_{IC,RF}(ic,rf)$

Using the information described ONLY in this subquestion, derive the expression for the joint exceedance probability  $P[IC > ic, RF > rf]$ . You may want to draw a diagram to assist you.



Use the grid below if you run out of space for any exercise.  
In that case, please indicate so at the original answer field.

